Department of Mechatronics Engineering
B. Sc. Engineering 1st Year 1st Term Examination, 2019

Ch 1131 (Chemistry)

Time: 3 Hours

Total Marks: 210

N.B.: i) Answer any THREE questions from each section in separate scripts.ii) Figures in the right margin indicate full marks.iii) Assume reasonable data if any missing.

SECTION-A

	Derive the relation between the constant of equilibrium constant.	
1(a)	What type of bonding involves in silicon? Draw the crystal structure of silicon and discuss its technological applications in our daily life.	10
1(b),	Draw the molecular orbital diagram of O_2 and predict about bond order and magnetic properties.	10
1(c)	"Metal has high density" - Explain based on its crystal structures.	08
1(d)	Draw the structure of d orbitals and mention its impact on d - d splitting.	07
2(a)	Define corrosion. Write the reaction mechanism of 'Environmental corrosion'.	10
2(b)	Discuss the effect of humidity and dust particle on the rate of atmospheric corrosion.	08
2(c)	What is local cell corrosion? Write down the impacts of local cell corrosion in our daily life.	10
2(d)	Write short note on "Sacrificial Anode".	07
3(a)	What is mass defect? How it is related to the binding energy and stability of the nucleus, explain with diagram.	10
3(b)	Draw a thematic diagram of a nuclear power plant and explain how it works.	10
3(c)	The mass of ¹⁶ ₈ 0 is 15.994910 amu. Calculate its binding energy per nucleon.	07
3(d)	What are the pros and cons of having nuclear power plants in Bangladesh?	08
4(a)	Explain the terms: (i) Phase (ii) Component (iii) Degree of freedom and (iv) Triple point.	12
4(b)	"Water is the best solvent" - Explain based on H-bond concepts.	10
4(c)	Describe one component system of water with the help of the phase diagram.	13
	SECTION-B	
5(a)	Explain the terms lowering of vapour pressure and relative lowering of vapour pressure. What are their units?	10
5(b)	Derive a relationship between the elevation in boiling point of a solution and the mole fraction of the solute from thermodynamic considerations.	08

- 09 State and derive Raoult's law for lowering of vapour pressure. How is this law used for the determination of molecular mass of a non-volatile solute? What is isotonic solution? Calculate the Ospmotic pressure of a 5% solution of 08 glucose (mol wt = 180) at 18°C. What is meant by chemical equilibrium constant? Derive the expression for 10 6(a) equilibrium constant of the reaction: $H_2(g) + I_2(g) \rightleftharpoons 2HI(g).$ 08 Derive the relation between free energy change and equilibrium constant. 07 13.5 mL of HI is produced by the interaction of 8.1mL of Hydrogen and 9.3 mL 6(c) of Iodine vapour at 444°C. Calculate the equilibrium constant at this temperature of the reaction - $H_2(g) + I_2(g) \Longrightarrow 2HI(g).$ 10 What is meant by solvent extraction? Prove that the efficiency of multiple 6(d) extraction process by same amount of solvent is higher than that of single one. What is meant by the rate of a reaction? How does the rate constant for a reaction 12 7(a) vary with the temperature? 08 Differentiate between order and molecularity of a reaction. 7(b)
 - 07 For a certain first order reaction t_{1/2} is 100 sec. How long will it take for the 7(c)reaction to be completed 75%? 08 "The reactions of higher order rate" - explain. 7(d)
 - Why chemical equilibrium is called a dynamic equilibrium? 8(a) 08 8(b) Prove that under specified condition a second order reaction follows the kinetics of a first order reaction.

08

10

What is steady state approximation? "Steady state approximation reduces the 09 8(c) complexity of a reaction" - Explain.

8(d)

Determine the rate of the reaction, $A + 2B \rightarrow C$, from following data: Initial rate [C] (in M/S) Exp. No. Initial [A] (in M) Initial [B] (in M) 5.5×10^{-6} 1 0.1 0.1 2.2×10^{-5} 2 0.2 0.1 0.1 8.8×10^{-5} 3 0.4 1.65×10^{-5} 4 0.1 0.3 3.3×10^{-5} 5 0.1 0.6

Department of Mechatronics Engineering

B.Sc. Engineering 1st Year 1st Term Examination, 2019

EE 1131 (Electrical Circuits)

Time: 3 Hours

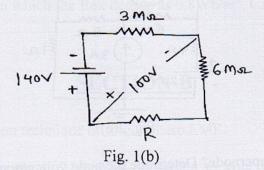
Total Marks: 210

N.B.: i) Answer any THREE questions from each section in separate scripts.

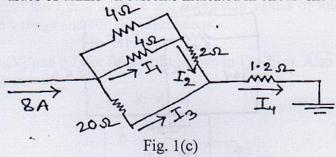
ii) Figures in the right margin indicate full marks.

SECTION-A

- 1(a) Define Branch and Node. State and explain Kirchhoff's voltage and current law. 05
- 1(b) Using voltage divider rule, find the value of unknown resistance shown in Fig. 10 1(b).



1(c) Determine the values of unknown currents indicated in circuit shown in Fig. 1(c).



1(d) Determine the value of power delivered to the load $R_L = 6\Omega$ shown in Fig. 1(d).

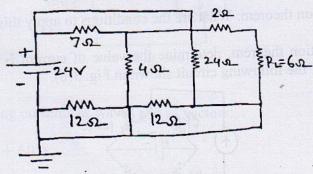
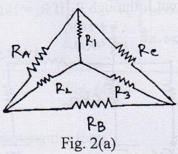
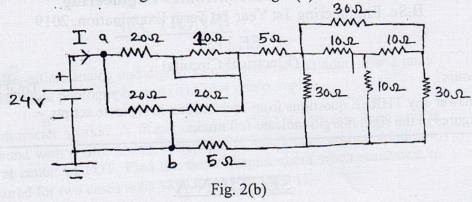


Fig. 1(d)

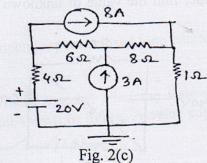
2(a) Deduce the expression of R₁, R₂, R₃ in terms of R_A, R_B, R_C for the following circuit shown in Fig. 2(a).



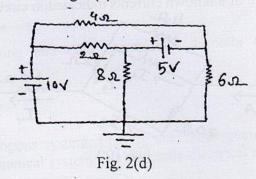
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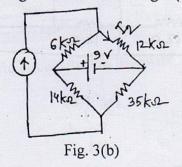
2(c) Define mesh. Find the mesh current of the circuit shown in Fig. 2(c) by using mesh analysis.



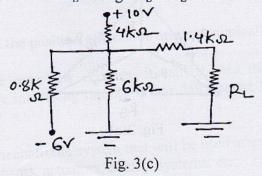
2(d) What is meant by supernode? Determine the node voltages and branch current for the following circuit shown in Fig. 2(d).

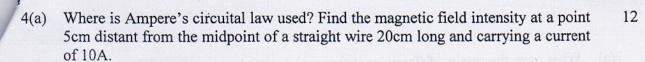


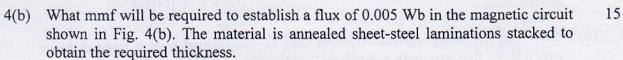
- 3(a) State superposition theorem. What are the conditions to apply this theorem?
- 3(b) Using superposition theorem, determine the value of current I_2 flowing through $12k\Omega$ resistor for the following circuit shown in Fig. 3(b).

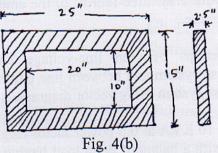


3(c) Determine the Thevenin equivalent circuit for the load R_L as shown in Fig. 3(c), hence find the value of current I_L through R_L if $R_L = 1k\Omega$.









4(c) A straight conductor which carries a current of 50A lies perpendicular to the lines of a magnetic field in which the flux density is 0.8Wb/m². Calculate the force per meter of conductor.

SECTION-B

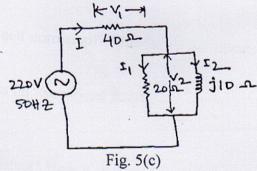
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10

06

07

- 5(a) Explain the generation technique of single-phase EMF.
- 5(b) A sinusoidal AC supply of 220∠0° is connected to your house for driving an electrical load. The resistance and inductance of the load are 10Ω and 10mH, respectively. Find the r.m.s, average and maximum values of load current. Also write down the voltage and current expressions.
- 5(c) Find I, I₁, I₂,V₁,V₂ and p.f. for the circuit shown in Fig. 5(c). Also draw the vector diagram for the circuit.

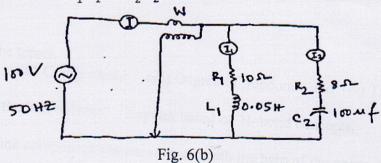


6(a) Add the following currents as waves and as vectors:

 $i_1 = 5\sin\omega t$

 $i_2 = 10\sin(\omega t + 60^\circ)$

6(b) Find the readings of ammeters I₁, I₂, I and of wattmeter W of Fig. 6(b). Compare the readings of W with I₁²R₁ and I₂²R₂.



6(c) Express $\log_e \sqrt{\frac{125\angle -90^\circ}{5\angle 90^\circ}}$ in rectangular form.

6(d) Explain the power factor correction technique for an electrical circuit.

7(a)	What are the main differences between single-phase and three-phase EMF generations?	05
7(b)	Show that the same amount of power may be transmitted over a fixed distance with a fixed line loss with only three-fourths of the amount of copper that would be required for single-phase.	.07
7(c)	Establish the relationships between line-voltage and phase voltage of a Y-connected three-phase system and between line current and phase current of a Δ -connected three-phase system using vector diagram.	08
7(d)	A 3-phase motor takes 10 KVA at 0.6 power factor lagging from a source of 220 volts. It is in parallel with a balanced delta load having 16Ω resistance and 12Ω capacitive reactance in series in each phase. Find the total volt-amperes, power, line current and power factor of the combination.	15
8(a)	What are the advantages of neutral wire connection in a 3-phase Y-connected system?	05
8(b)	Explain two-wattmeter method for measuring three phase power for a balanced Y-connected load with proper diagrams.	15
8(c)	What is meant by phase sequence? Explain the two-lamp method for the determination of phase sequence of a three phase system with necessary phasor diagram.	15

S(c) Find I, I, I, V, V, and p.I gor Percire diagram for the circuits of

Department of Mechatronics Engineering B. Sc. Engineering 1st Year 1st Term Examination, 2019

Hum 1131

(Sociology and Engineering Ethics)

Time: 3 Hours Total Marks: 210

N.B.: i) Answer any THREE questions from each section in separate scripts. ii) Figures in the right margin indicate full marks.

	SECTION-A	
1(a)	"Sociology is the science of social institution" – do you agree this statement? Give reason in favor of your opinion.	10
1(b)	Explain importance of Sociological knowledge for the students of Mechatronics Engineering department.	10
1(c)	Explain the role of industrial revolution behind origin and development of Sociology as a distinct discipline.	15
2(a)	Describe contribution of Auguste Comte behind origin and development of sociology as a science.	10
2(b)	Explain scope of Sociology with relevant example from our country.	10
2(c)	What is meant by Society? Explain types of Society with example.	15
3(a)	What is meant by Institution? Explain functions of Institution with example.	13
3(b)	What is Community? Distinguish between role of urban and rural communities in Bangladesh.	12
3(c)	What is Culture? Explain the elements of Culture.	10
4(a)	Explain key differences among Capitalism, Socialism, and Communism.	10
4(b)	"Rapid urbanization is blessing for any country" – do you agree with this statement? Give reasons in favor of your opinion.	15
4(c)	What is Social change? Discuss the impact of globalization on family and marriage.	10
	SECTION-B	

5(a)	What is meant by "Ethics" and "Morality"? "Ethics is the science of ultimate good" – Explain.	12
5(b)	"Morality is indispensable to religion" – Discuss.	08
5(c)	What is globalization? Do you believe that it's good for us? Give reasons in favor of your opinion	15

6(a)	What are the roles of code of Ethics? Discuss the IEEE or NSPE fundamental codes of ethics.	15
6(b)	Is Engineering a profession?-Justify. Describe the main characteristics of profession.	10
6(c)	Define Engineering Ethics? What are the factors influence engineering decision?	10
7(a)	What is meant by Utilitarianism? "Greatest happiness of the greatest number of	12
7(b)	people" - Explain. What is the difference between duty and responsibility? As an Engineer what is	08
7(c)	your responsibility? What is Human Right? Describe about the universal declaration of Human Rights	15
8(a)	Explain about three approaches of Respect for Persons Honesty.	10
8(b)		15
8(c)	Discuss some professional characteristics of a good engineer.	10

(a) . What is meant by farthmont Explain that noise of had moon is an explain.

Department of Mechatronics Engineering
B. Sc. Engineering 1st Year 1st Term Examination, 2019
Math 1131

(Calculus and Geometry)

Time: 3 Hours

Total Marks: 210

- N.B.: i) Answer any THREE questions from each section in separate scripts.
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SECTION-A

- Define limit and continuity of a function. A function f(x) is defined as follows: 15 $f(x) = 1 + \sin x \qquad \text{for } 0 \le x < \pi/2$ $= 2 + (x \pi/2)^2 \qquad \text{for } x \ge \pi/2$ Discuss the continuity and differentiability of f(x) at $x = \pi/2$.
- 1(b) State Rolle's theorem. Is the Rolle's theorem applicable to the function $f(x) = x^2 + 5x 6$ in the interval (-6, 1)?
- 1(c) If $f(x) = \left(\frac{a+x}{b+x}\right)^{a+b+2x}$, show that $f'(0) = \left(2\log\frac{a}{b} + \frac{b^2 a^2}{ab}\right)\left(\frac{a}{b}\right)^{a+b}$.
- 2(a) State Leibnitz theorem. If $logy = tan^{-1}x$, show that $(1+x^2)y_{n+2} + (2nx+2x-1)y_{n+1} + n(n+1)y_n = 0$.
- 2(b) State Mean Value theorem. Verify Mean Value theorem for the function $f(x) = 2x x^2$ in the interval (0, 1).
- 2(c) Define homogeneous function and harmonic function.

 If $u = f(x^2 + 2yz, y^2 + 2zx)$, show that $(y^2 zx)\frac{\partial u}{\partial x} + (x^2 yz)\frac{\partial u}{\partial y} + (z^2 xy)\frac{\partial u}{\partial z} = 0.$
- 3(a) If $V = (ax + by)^2 (x^2 + y^2)$, where $a^2 + b^2 = 2$, show that $V_{xx}^* + V_{yy} = 0$.
- 3(b) Find the maximum and minimum values of $12(logx + 1) + x^2 10x + 3$.
- 3(c) Find the asymptotes of $x^3 2y^3 + xy(2x y) + y(x y) + 1 = 0$.
- 4(a) If $x\cos\alpha + y\sin\alpha = P$ touch the curve $\frac{x^m}{a^m} + \frac{y^m}{b^m} = 1$ show that $(a\cos\alpha)^{\frac{m}{m-1}} + (b\sin\alpha)^{\frac{m}{m-1}} = P^{\frac{m}{m-1}}.$
- Define subtangent and subnormal. Show that for the curve $by^2 = (a + x)^3$, the square of the subtangent varies as the subnormal.
- 4(c) Define curvature. Find the radius of curvature of the astroid $x^{2/3} + y^{2/3} = a^{2/3}$ at any point.

Department of Mechatronics Engineering

B. Sc. Engineering 1st Year 1st Term Examination, 2019

Hum 1131 (Sociology and Engineering Ethics)

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Department of Mechatronics Engineering

B. Sc. Engineering 1st Year 1st Term Examination, 2019

MTE 1101

(Mechatronic Systems)

Time: 3 Hours Total Marks: 210

N.B.: i) Answer any THREE questions from each section in separate scripts.

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iii) Assume reasonable data if any missing.

SECTION-A

1(a)	Explain in brief the theme of Mechatronics Engineering. Mention the difference between conventional and mechatronic approach of a system design.	11
1(b)	What are the key elements of a Mechatronics system? Demonstrate in brief the concept of mechtronics system with the help of block diagram.	()12
1(c)	Give some example of Mechatronics system. Write down some benefit and demerits of mechatronic design approach.	12
2(a)	Draw the block diagram of generalized measurement system and explain in details. Mention the advantages of electronic instruments over mechanical instruments.	10
2(b)	Explain the terms: (i) Sensitivity, (ii) Reproducibility, (iii) Dead time, and (iv) Loading effect.	08
2(c)	A voltage has a true value of 1.50 volt. An analog indicating instrument with a scale range of $0-2.50$ volt shows a voltage of 1.46 volt. What are the values of absolute error and correction? Express the error as a function of true value and full scale deflection.	07
2(d)	Define relative limiting error. Three resistors have the following ratings: $R_1 = 37~\Omega \pm 5\%$, $R_2 = 75~\Omega \pm 5\%$, $R_3 = 50~\Omega \pm 5\%$. Find the magnitude and limiting error in ohm and percent of the resistance of these resistances connected in series.	10
	Draw the f - 1 and occurs referring the form of the first and the first	
3(a)	What is sensor? Why it is necessary in mechatronics?	07
3(b)	Give some example of commonly used sensors in Robotics. What are the basic elements of a temperature sensor? Compare IR sensor and ultrasonic sensor with respect to object detection.	10
3(c)	'A metal detector is a proximity sensor', justify with proper illustration.	10
(3(d)	What will be the contribution of a Mechatronics Engineer to develop a gesture controlled Robot?	08
4(a)	Design a mechatronic device (Robot) for household activities with necessary actuators. Mention the working area of the robot and name of the actuators.	08
4(b)	Explain the working principle of a selected actuator and justify its use in the particular device.	15
4(c)	Describe and differentiate hydraulic, electric and pneumatic actuators with necessary examples.	12

SECTION-B

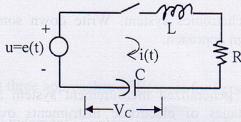
- Define and differentiate analog and digital signal. Mention the domain and range of (i) Black and white photograph, and (ii) Color photograph.

12

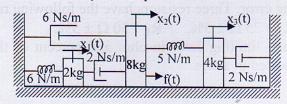
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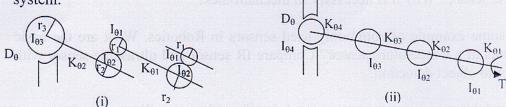
- 5(b) How a potentiometer works? A linear resistance POT is 50 mm long and is uniformly wound with a wire having resistance 10 k Ω . Under normal condition, the slider is at center of POT. Find the linear displacement when resistance of POT as measured for two cases is (i) 3850 Ω and (ii) 7560 Ω .
- 5(c) Deduce the equation of maximum sensitivity of a Wheatstone bridge. 12
- Define control system. Describe open loop and closed loop control system block 6(a) 11 diagram with example.
- 6(b) What are the methods to describe a system? Find the state space model and 14 transfer function of a RLC circuit shown in figure. Assume capacitor voltage as



- What are signal conditioning and data acquisition? Explain their role in 6(c) 10 mechatronics system.
- 7(a) Define the concept of analogous system. List the analogous quantities between 11 rotational translational mechanical system and hydraulic-electrical system.
- Find the analogous electrical network for the following mechanical translational 12 system. Also write down the system equation.



Draw the f - i analogous electric circuit for the following mechanical rotational system.



- 8(a) Explain how can control the position of Robotic arm automatically.
- 8(b)Comparing the lifestyle over few decades, it can be said that application of 12 mechatronic systems are increasing rapidly in our daily house hold and medical area. – Justify.
- Forecast and design a mechatronic system that will be used after 2040. Explain its 8(c) 13 technical details like sensors, actuators, control systems, etc.